

## MATLAB Computer Session 3: State Space Modelling

Dimitris Korobilis and I have created a website containing Matlab code for Bayesian estimation of VARs and other models popular with empirical macroeconomists (see [http://personal.strath.ac.uk/gary.koop/bayes\\_matlab\\_code\\_by\\_koop\\_and\\_korobilis.html](http://personal.strath.ac.uk/gary.koop/bayes_matlab_code_by_koop_and_korobilis.html)). It is associated with our monograph. Koop, G. and Korobilis, D. (2010). *Bayesian Multivariate Time Series Methods for Empirical Macroeconomics* which is available on this website. The monograph and website provide additional material and background detail about this exercise. However, I have put the material directly used in this exercise on the website associated with this course: [http://personal.strath.ac.uk/gary.koop/BoK\\_course.html](http://personal.strath.ac.uk/gary.koop/BoK_course.html)

### MATLAB Exercises:

#### *Inflation Persistence in the US*

Use the unobserved components model of Stock and Watson (2007) “Why Has U.S. Inflation Become Harder to Forecast?,” *Journal of Money, Credit and Banking*. The program, TVP\_AR\_SW.m, contains code for the model given in their equations (8) - (11) which we replicate here:

$$\begin{aligned}\pi_t &= \tau_t + \eta_t, \quad \eta_t \sim N(0, \sigma_t^\eta) \\ \tau_t &= \tau_{t-1} + \varepsilon_t, \quad \varepsilon_t \sim N(0, \sigma_t^\varepsilon) \\ \log(\sigma_t^\eta) &= \log(\sigma_{t-1}^\eta) + v_t^\eta, \quad v_t^\eta \sim N(0, \gamma_1) \\ \log(\sigma_t^\varepsilon) &= \log(\sigma_{t-1}^\varepsilon) + v_t^\varepsilon, \quad v_t^\varepsilon \sim N(0, \gamma_2)\end{aligned}$$

We provide data on three measures of inflation ( $\pi_t$ ), CPI inflation, PPI inflation and GDP deflator inflation. Use the code to plot trend inflation ( $\tau_t$ ) and the volatilities  $\sigma_t^\eta$  and  $\sigma_t^\varepsilon$ . Is there evidence that  $\sigma_t^\eta$  is varying over time? Is there evidence that  $\sigma_t^\varepsilon$  is varying over time.?

Optional: Stock and Watson (2007) also estimate a model (see their equations (5) and (6)) where state and measurement equation variances are constant ( $\sigma_t^\eta = \sigma^\eta$  and  $\sigma_t^\varepsilon = \sigma^\varepsilon$ ). You can also consider models where there is stochastic volatility in one equation but not the other (i.e.  $\sigma_t^\varepsilon = \sigma^\varepsilon$  but  $\sigma_t^\eta$  is time varying or  $\sigma_t^\eta = \sigma^\eta$  but  $\sigma_t^\varepsilon$  is time varying). Modify the code to estimate these models and compare results to the full model.